

## Exercise 8

A spring has a mass of 1 kg and its damping constant is  $c = 10$ . The spring starts from its equilibrium position with a velocity of 1 m/s. Graph the position function for the following values of the spring constant  $k$ : 10, 20, 25, 30, 40. What type of damping occurs in each case?

### Solution

The equation of motion for a mass attached to a spring and a dashpot is

$$-c \frac{dx}{dt} - kx = m \frac{d^2x}{dt^2}.$$

Bring all terms to the left side.

$$m \frac{d^2x}{dt^2} + c \frac{dx}{dt} + kx = 0 \quad (1)$$

This is a linear homogeneous ODE, so its solutions are of the form  $x = e^{rt}$ .

$$x = e^{rt} \rightarrow \frac{dx}{dt} = re^{rt} \rightarrow \frac{d^2x}{dt^2} = r^2e^{rt}$$

Plug these formulas into equation (1).

$$m(r^2e^{rt}) + c(re^{rt}) + k(e^{rt}) = 0$$

Divide both sides by  $e^{rt}$ .

$$mr^2 + cr + k = 0 \quad (2)$$

Overdamping occurs when  $c^2 - 4mk > 0$ , that is, when  $k = 10$  and  $c = 20$ . In this case, the solution to equation (2) is

$$r = \frac{-c \pm \sqrt{c^2 - 4mk}}{2m}$$

$$r = \left\{ \frac{-c - \sqrt{c^2 - 4mk}}{2m}, \frac{-c + \sqrt{c^2 - 4mk}}{2m} \right\}.$$

Two solutions to the ODE are

$$\exp\left(\frac{-c - \sqrt{c^2 - 4mk}}{2m}t\right) \quad \text{and} \quad \exp\left(\frac{-c + \sqrt{c^2 - 4mk}}{2m}t\right).$$

By the principle of superposition, then, the general solution to equation (1) is

$$x(t) = C_1 \exp\left(\frac{-c - \sqrt{c^2 - 4mk}}{2m}t\right) + C_2 \exp\left(\frac{-c + \sqrt{c^2 - 4mk}}{2m}t\right),$$

where  $C_1$  and  $C_2$  are arbitrary constants. Differentiate it with respect to  $t$  to get the velocity.

$$\frac{dx}{dt} = C_1 \frac{-c - \sqrt{c^2 - 4mk}}{2m} \exp\left(\frac{-c - \sqrt{c^2 - 4mk}}{2m}t\right)$$

$$+ C_2 \frac{-c + \sqrt{c^2 - 4mk}}{2m} \exp\left(\frac{-c + \sqrt{c^2 - 4mk}}{2m}t\right)$$

Apply the initial conditions,  $x(0) = 0$  and  $x'(0) = 1$ , to determine  $C_1$  and  $C_2$ .

$$x(0) = C_1 + C_2 = 0$$

$$\frac{dx}{dt}(0) = C_1 \frac{-c - \sqrt{c^2 - 4mk}}{2m} + C_2 \frac{-c + \sqrt{c^2 - 4mk}}{2m} = 1$$

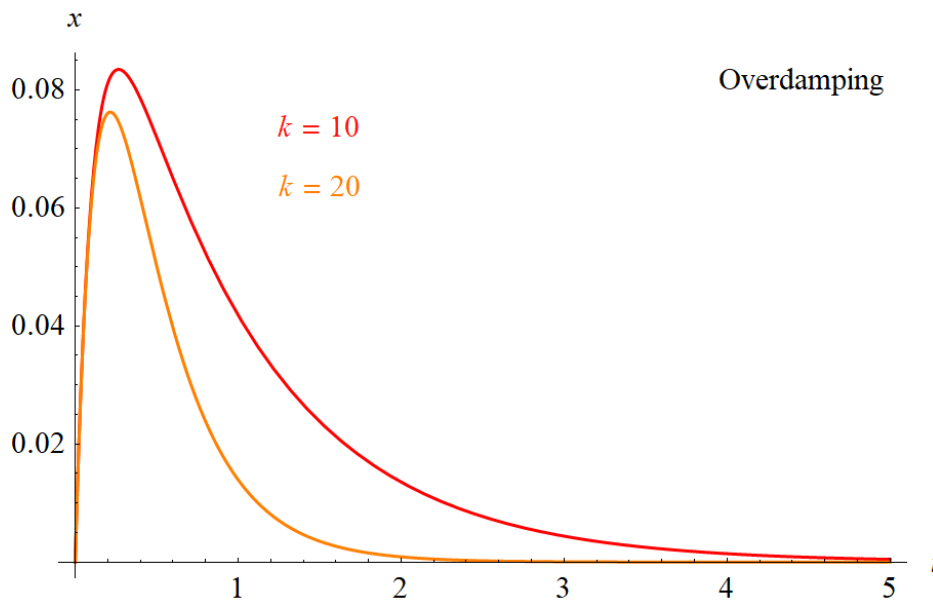
Solving this system of equations yields

$$C_1 = -\frac{m}{\sqrt{c^2 - 4mk}} \quad \text{and} \quad C_2 = \frac{m}{\sqrt{c^2 - 4mk}},$$

meaning the displacement from equilibrium in overdamping is

$$x(t) = -\frac{m}{\sqrt{c^2 - 4mk}} \exp\left(\frac{-c - \sqrt{c^2 - 4mk}}{2m}t\right) + \frac{m}{\sqrt{c^2 - 4mk}} \exp\left(\frac{-c + \sqrt{c^2 - 4mk}}{2m}t\right).$$

Plug in  $m = 1$  kg and  $c = 10$  N/m and graph  $x(t)$  versus  $t$  for  $k = 10$  N · s/m and  $k = 20$  N · s/m.



Critical damping occurs when  $c^2 - 4mk = 0$ , that is, when  $k = 25$ . In this case, the solution to equation (2) is

$$r = -\frac{c}{2m}$$

$$r = \left\{ -\frac{c}{2m} \right\}.$$

Two solutions to the ODE are

$$\exp\left(-\frac{c}{2m}t\right) \quad \text{and} \quad t \exp\left(-\frac{c}{2m}t\right).$$

By the principle of superposition, then, the general solution to equation (1) is

$$\begin{aligned} x(t) &= C_3 \exp\left(-\frac{c}{2m}t\right) + C_4 t \exp\left(-\frac{c}{2m}t\right) \\ &= \exp\left(-\frac{c}{2m}t\right) (C_3 + C_4 t), \end{aligned}$$

where  $C_3$  and  $C_4$  are arbitrary constants. Differentiate it with respect to  $t$ .

$$\frac{dx}{dt} = -\frac{c}{2m} \exp\left(-\frac{c}{2m}t\right) (C_3 + C_4t) + \exp\left(-\frac{c}{2m}t\right) (C_4)$$

Apply the initial conditions,  $x(0) = 0$  and  $x'(0) = 1$ , to determine  $C_1$  and  $C_2$ .

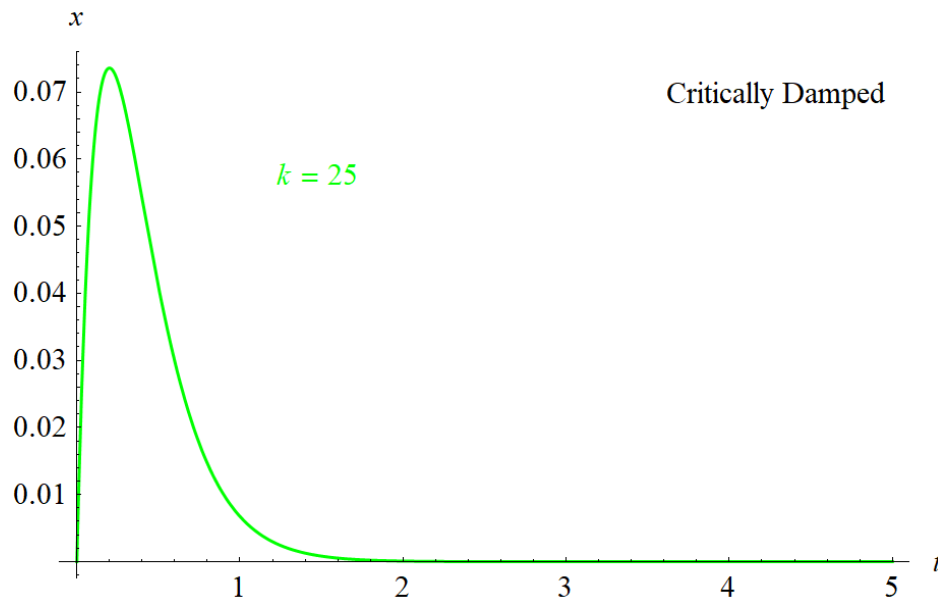
$$x(0) = C_3 = 0$$

$$\frac{dx}{dt}(0) = -\frac{c}{2m}C_3 + C_4 = 1$$

Solving this system of equations yields  $C_3 = 0$  and  $C_4 = 1$ , meaning the displacement from equilibrium in critical damping is

$$x(t) = t \exp\left(-\frac{c}{2m}t\right).$$

Set  $m = 1$  kg and  $c = 10$  N · s/m and graph  $x(t)$  versus  $t$ .



Underdamping occurs when  $c^2 - 4mk < 0$ , that is, when  $k = 30$  and  $k = 40$ . In this case, the solution to equation (2) is

$$r = \frac{-c \pm i\sqrt{4mk - c^2}}{2m}$$

$$r = \left\{ \frac{-c - i\sqrt{4mk - c^2}}{2m}, \frac{-c + i\sqrt{4mk - c^2}}{2m} \right\}.$$

Two solutions to the ODE are

$$\exp\left(\frac{-c - i\sqrt{4mk - c^2}}{2m}t\right) \quad \text{and} \quad \exp\left(\frac{-c + i\sqrt{4mk - c^2}}{2m}t\right).$$

By the principle of superposition, then, the general solution to equation (1) is

$$\begin{aligned}
 x(t) &= C_5 \exp\left(\frac{-c - i\sqrt{4mk - c^2}}{2m}t\right) + C_6 \exp\left(\frac{-c + i\sqrt{4mk - c^2}}{2m}t\right) \\
 &= C_5 e^{-ct/(2m)} \exp\left(-i\frac{\sqrt{4mk - c^2}}{2m}t\right) + C_6 e^{-ct/(2m)} \exp\left(i\frac{\sqrt{4mk - c^2}}{2m}t\right) \\
 &= C_5 e^{-ct/(2m)} \left(\cos\frac{\sqrt{4mk - c^2}}{2m}t - i\sin\frac{\sqrt{4mk - c^2}}{2m}t\right) + C_6 e^{-ct/(2m)} \left(\cos\frac{\sqrt{4mk - c^2}}{2m}t + i\sin\frac{\sqrt{4mk - c^2}}{2m}t\right) \\
 &= e^{-ct/(2m)} \left[ (C_5 + C_6) \cos\frac{\sqrt{4mk - c^2}}{2m}t + (-iC_5 + iC_6) \sin\frac{\sqrt{4mk - c^2}}{2m}t \right] \\
 &= e^{-ct/(2m)} \left( C_7 \cos\frac{\sqrt{4mk - c^2}}{2m}t + C_8 \sin\frac{\sqrt{4mk - c^2}}{2m}t \right),
 \end{aligned}$$

where  $C_7$  and  $C_8$  are arbitrary constants. Differentiate it with respect to  $t$  to get the velocity.

$$\begin{aligned}
 \frac{dx}{dt} &= -\frac{c}{2m} e^{-ct/(2m)} \left( C_7 \cos\frac{\sqrt{4mk - c^2}}{2m}t + C_8 \sin\frac{\sqrt{4mk - c^2}}{2m}t \right) \\
 &\quad + e^{-ct/(2m)} \left( -C_7 \frac{\sqrt{4mk - c^2}}{2m} \sin\frac{\sqrt{4mk - c^2}}{2m}t + C_8 \frac{\sqrt{4mk - c^2}}{2m} \cos\frac{\sqrt{4mk - c^2}}{2m}t \right)
 \end{aligned}$$

Apply the initial conditions,  $x(0) = 0$  and  $x'(0) = 1$ , to determine  $C_7$  and  $C_8$ .

$$x(0) = C_7 = 0$$

$$\frac{dx}{dt}(0) = -\frac{c}{2m} C_7 + C_8 \frac{\sqrt{4mk - c^2}}{2m} = 1$$

Solving this system of equations yields

$$C_7 = 0 \quad \text{and} \quad C_8 = \frac{2m}{\sqrt{4mk - c^2}},$$

meaning the displacement from equilibrium in underdamping is

$$\boxed{x(t) = \frac{2m}{\sqrt{4mk - c^2}} e^{-ct/(2m)} \sin\frac{\sqrt{4mk - c^2}}{2m}t.}$$

Plug in  $m = 1$  kg and  $c = 10$  N · s/m and graph  $x(t)$  versus  $t$  for  $k = 30$  N/m and  $k = 40$  N/m.

